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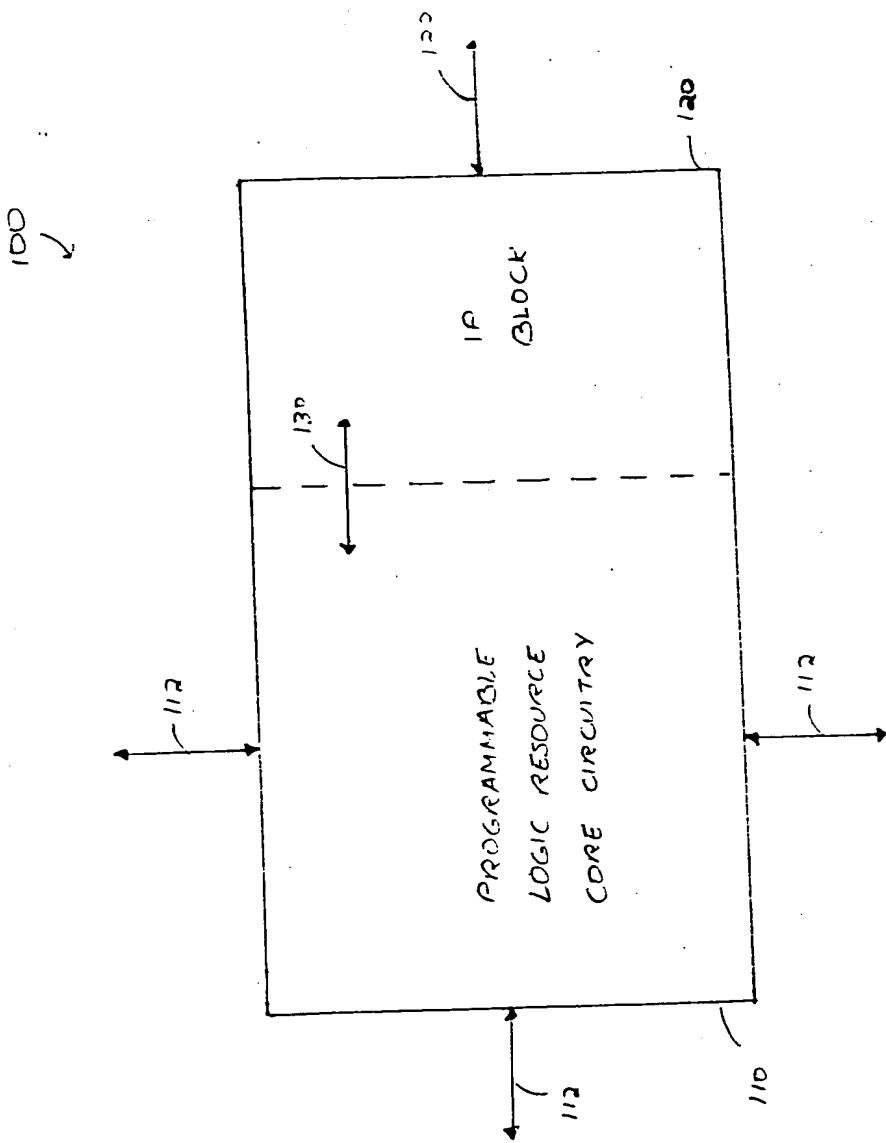


FIG. 1

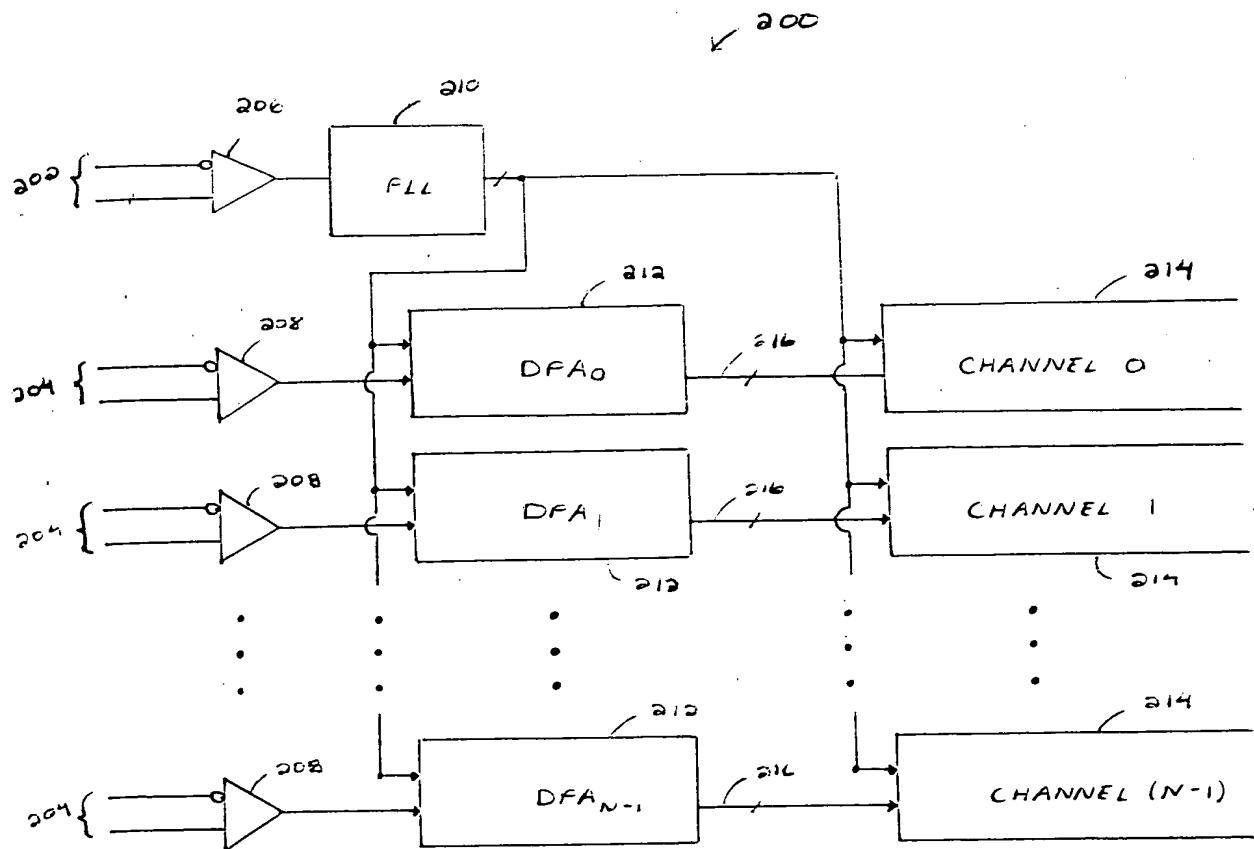


FIG. 2

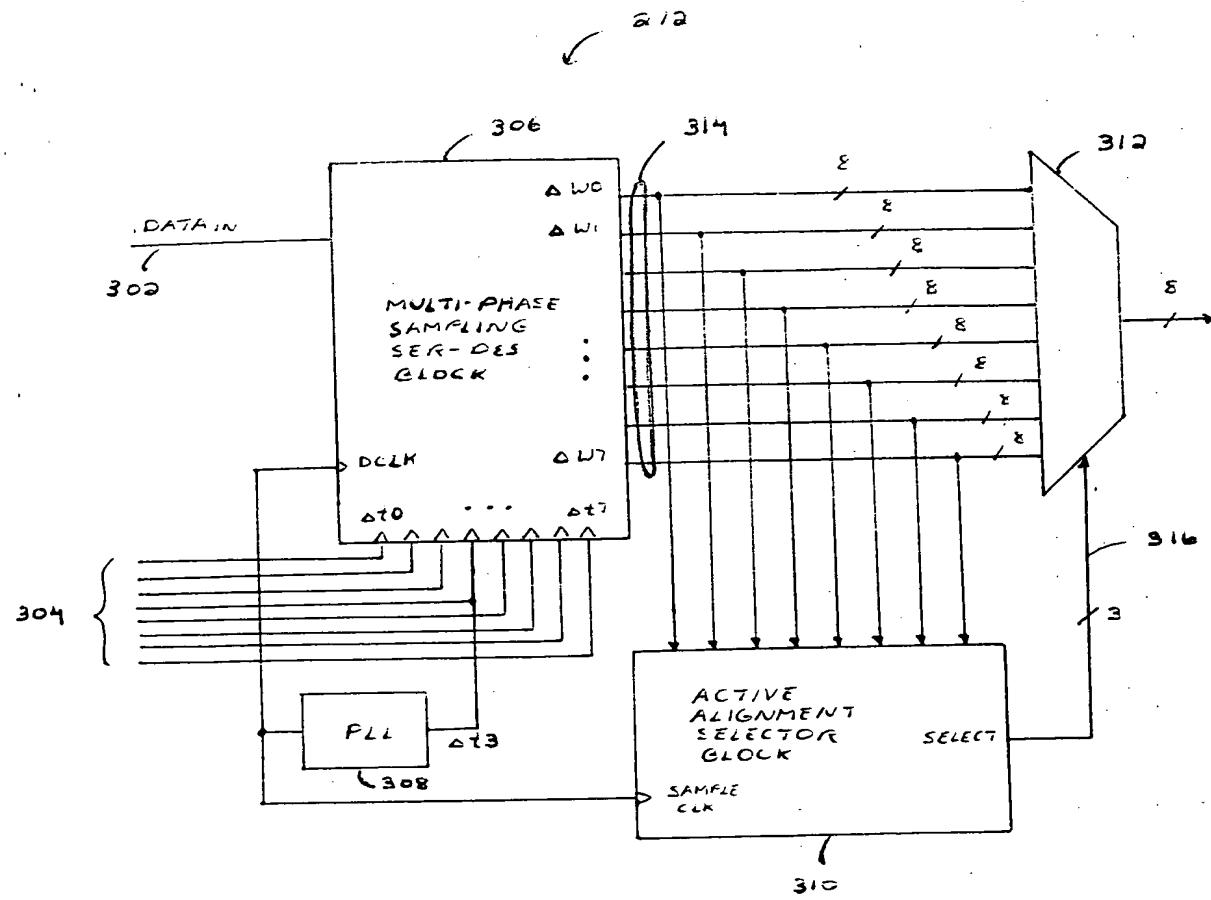


FIG. 3

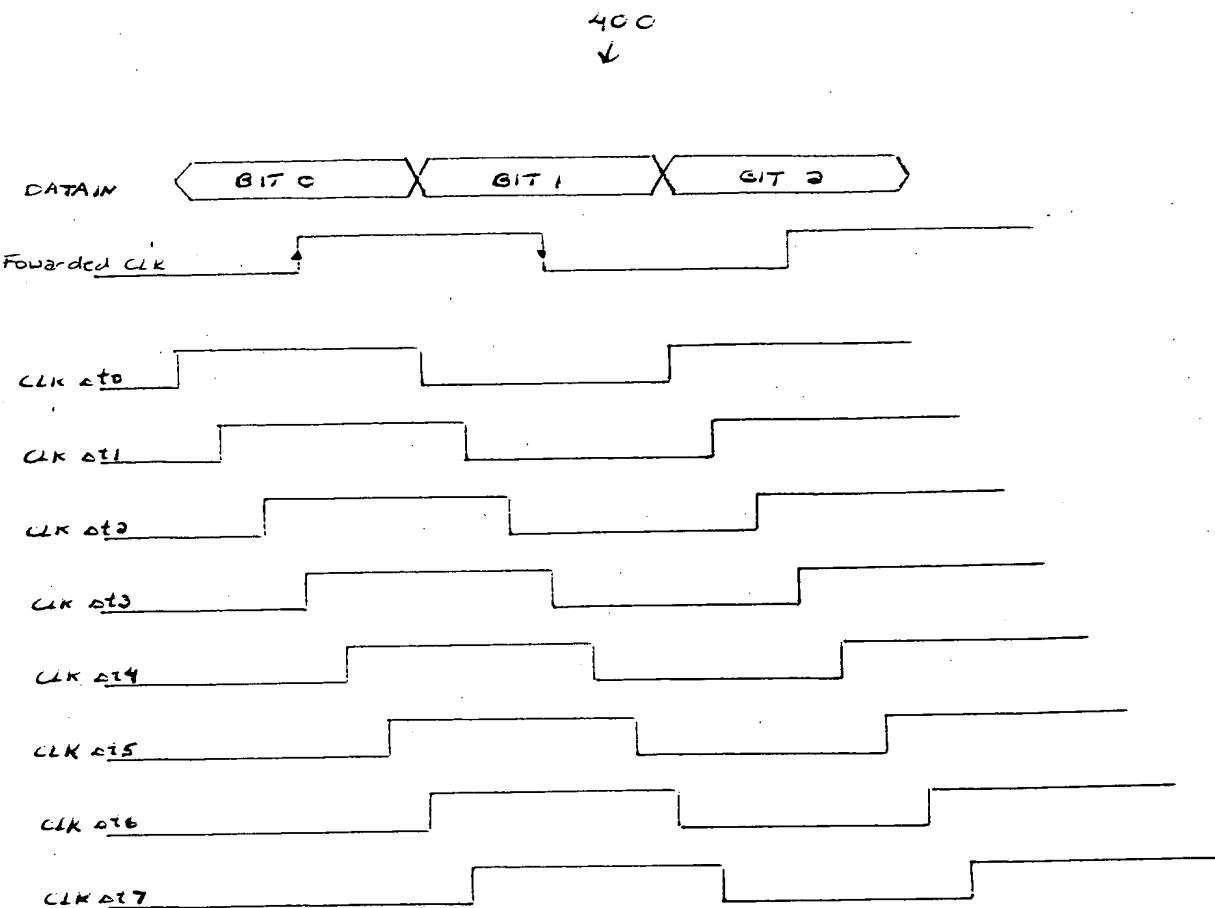


FIG 4A

450

✓

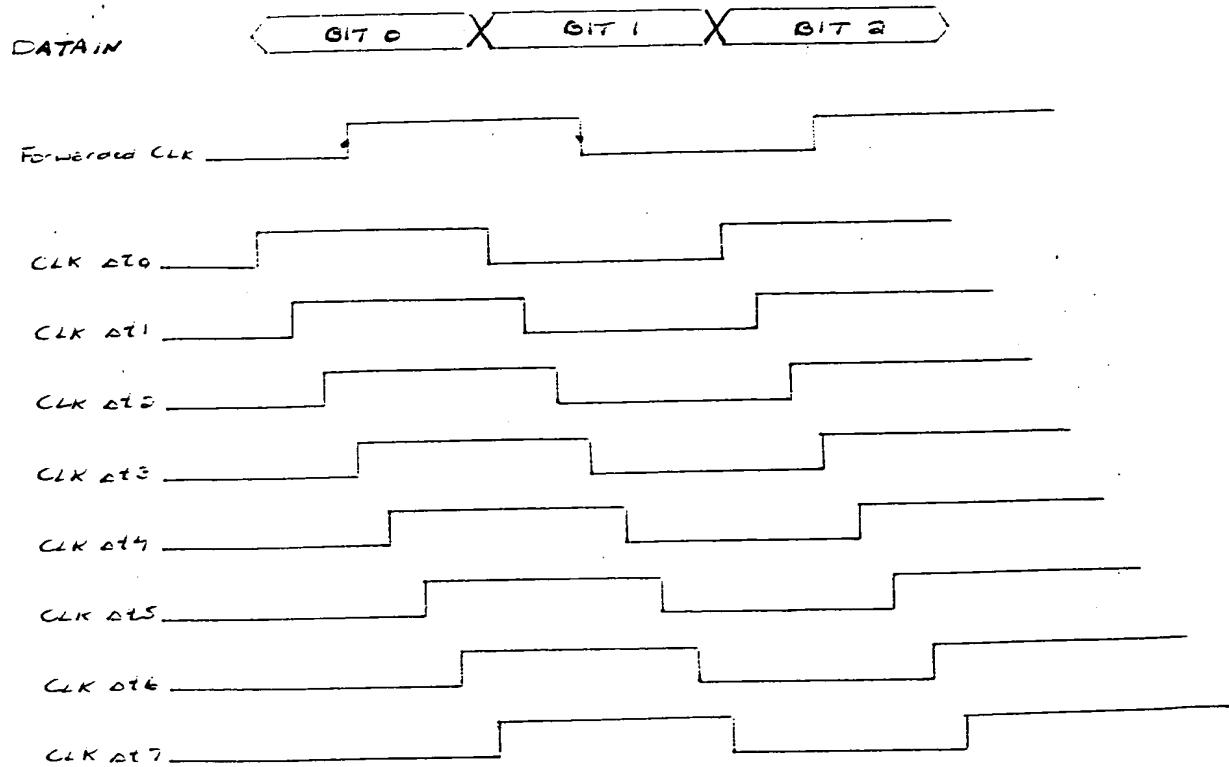


FIG. 4C

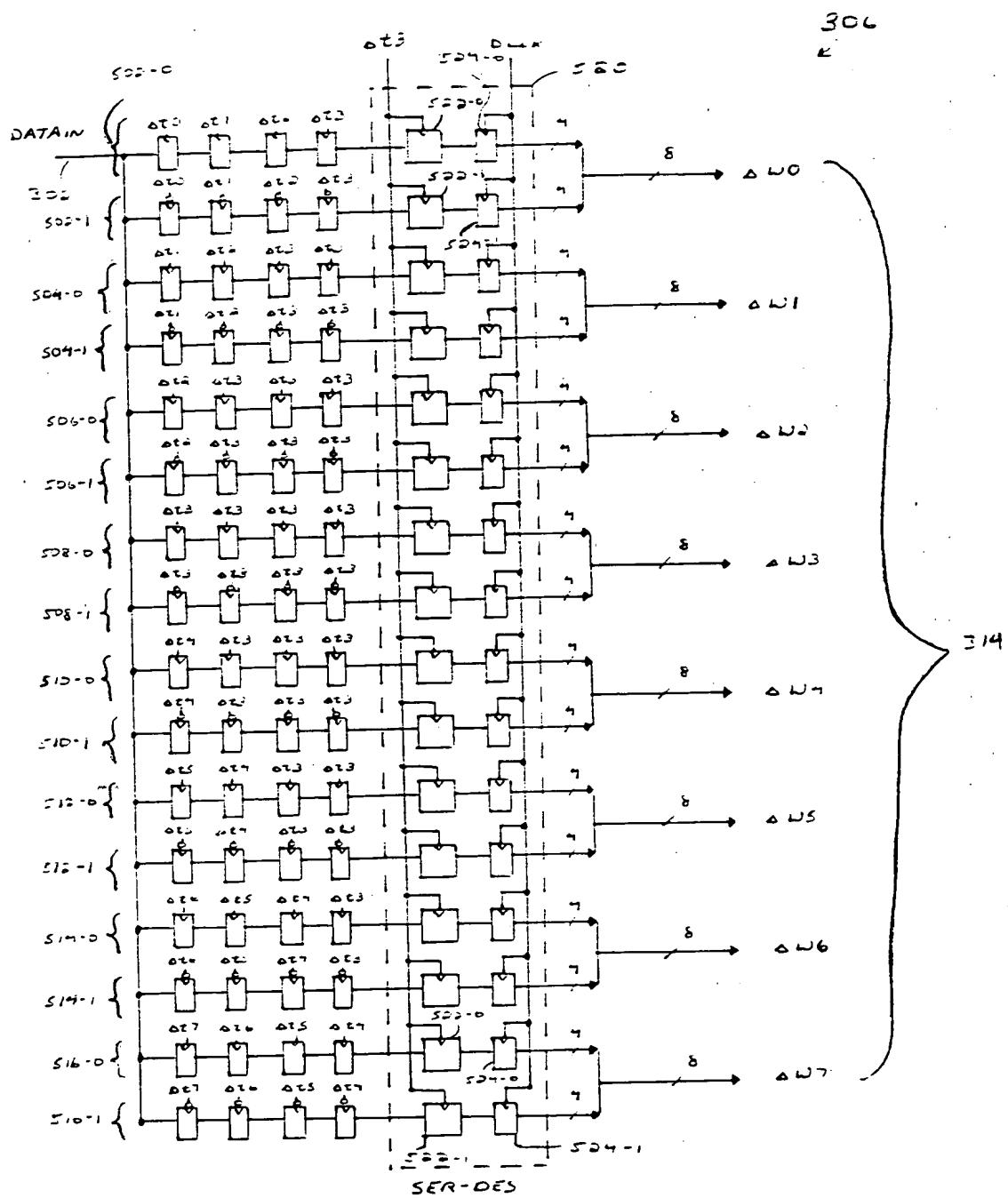
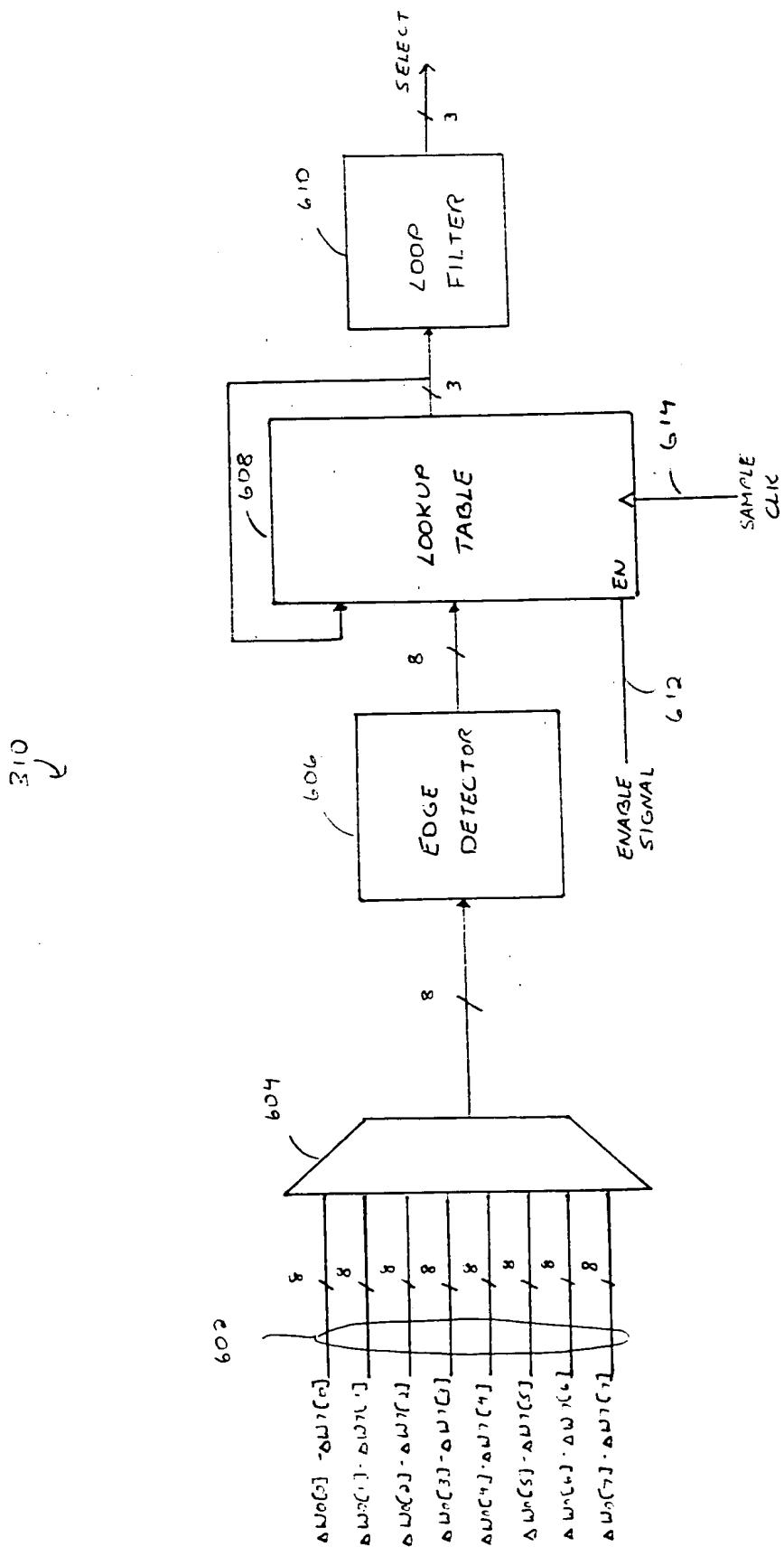


FIG. 5



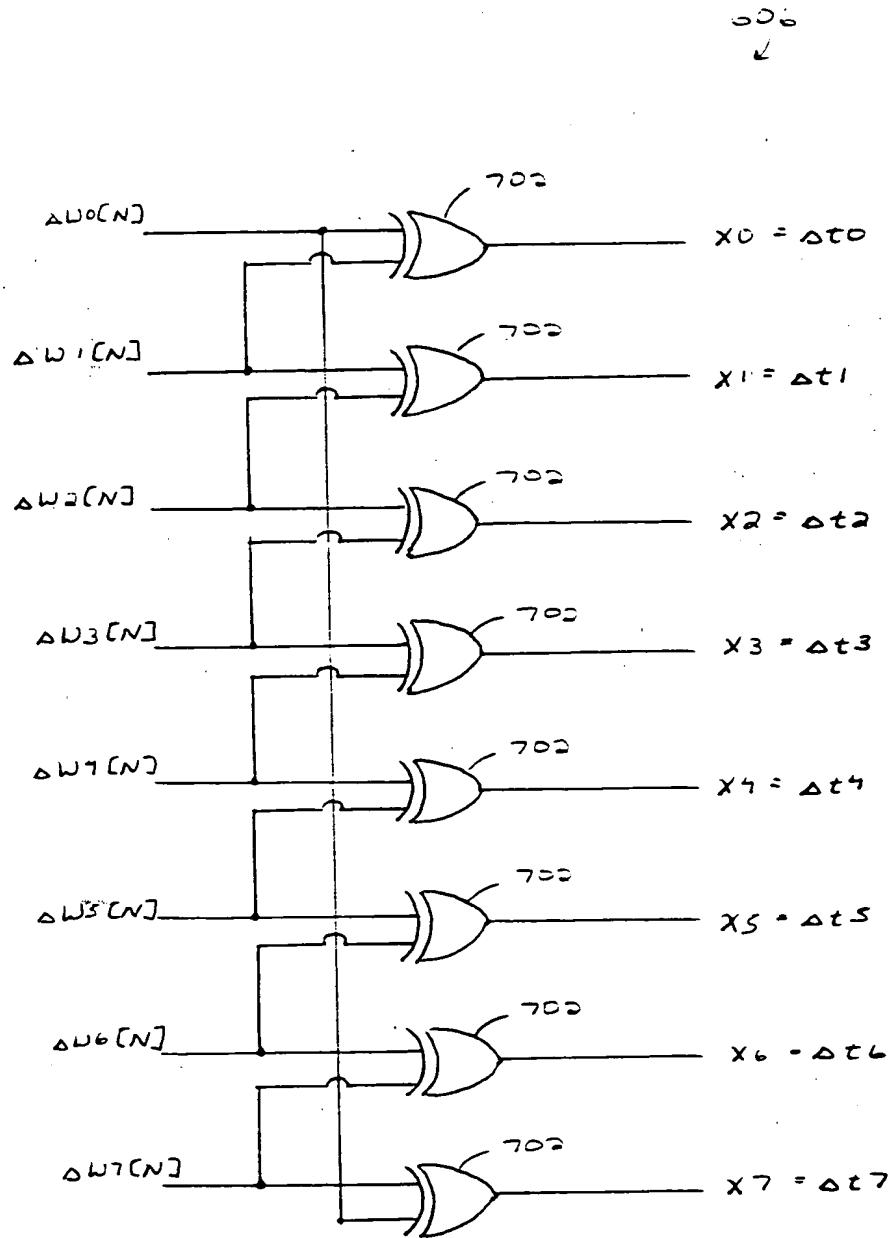


FIG. 7

802		804		808		808		810		812					
A(t)	B(t)	C(t)		$\Delta t0$	$\Delta t1$	$\Delta t2$	$\Delta t3$	$\Delta t4$	$\Delta t5$	$\Delta t6$	$\Delta t7$	A(t+1)	B(t+1)	C(t+1)	Comments
0	0	0		0	0	0	0	0	0	0	0	0	0	0	Hold Last State
0	0	1		0	0	0	0	0	0	0	0	0	0	1	Hold Last State
1	0	1		0	0	0	0	0	0	0	0	0	1	0	Hold Last State
2	0	1		0	0	0	0	0	0	0	0	0	1	1	Hold Last State
3	0	1		0	0	0	0	0	0	0	0	0	1	1	Hold Last State
4	1	0		0	0	0	0	0	0	0	0	0	0	0	Hold Last State
5	1	0		0	0	0	0	0	0	0	0	1	0	1	Hold Last State
6	1	0		0	0	0	0	0	0	0	0	1	0	1	Hold Last State
7	1	1		0	0	0	0	0	0	0	0	1	1	1	Hold Last State
0	0	0		0	0	0	0	0	0	0	0	0	0	1	11: Moves towards t3
1	0	0		0	0	0	0	0	0	0	0	1	0	0	12: Move towards t3
2	0	1		0	0	0	0	0	0	0	0	1	1	1	Center = t3
3	0	1		0	0	0	0	0	0	0	0	1	1	1	Center = t3
4	1	0		0	0	0	0	0	0	0	0	1	0	0	14: Move towards t3
5	1	0		0	0	0	0	0	0	0	0	1	0	0	15: Move towards t3
6	1	1		0	0	0	0	0	0	0	0	1	0	0	10: Move towards t3
7	1	1		0	0	0	0	0	0	0	0	0	0	0	
0	0	0		0	0	0	0	0	1	0	0	0	0	1	11: Move towards t2
1	0	0		0	0	0	0	0	1	0	0	1	0	0	Center = t2
2	0	1		0	0	0	0	0	1	0	0	0	1	0	Center = t2
3	0	1		0	0	0	0	0	0	0	0	0	1	1	13: Move towards t2
4	1	0		0	0	0	0	0	0	0	0	0	0	0	14: Move towards t2
5	1	0		0	0	0	0	0	0	0	0	1	0	1	15: Move towards t2
6	1	1		0	0	0	0	0	0	0	0	0	0	0	10: Move towards t2
7	1	1		0	0	0	0	0	0	0	0	1	0	0	

115.

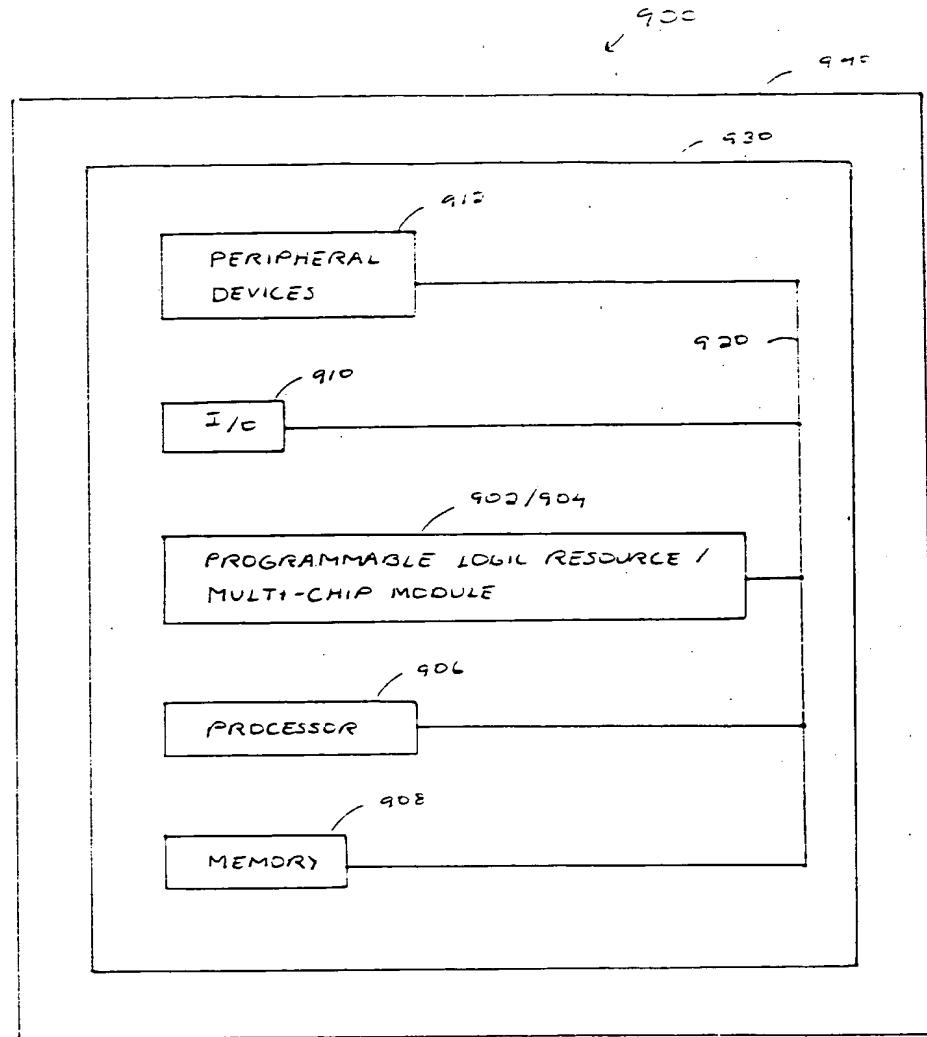


FIG. 9